Long time asymptotics of Toda shock waves

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Toda shock waves

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Der Wissenschaftsfonds.

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- Long-time asymptotics for the Toda shock problem: Non-overlapping spectra, with I. Egorova and J. Michor, Zh. Mat. Fiz. Anal. Geom. 14, 406–451 (2018)
- Long-time asymptotics for Toda shock waves in the modulation region, with I. Egorova, J. Michor, and A. Pryimak, arXiv:2001.05184



Motion of a chain of particles coupled via nonlinear springs



with potential

$$V(r) = e^{-r} + r - 1 = \frac{r^2}{2} - \frac{r^3}{6} + O(r^4).$$

Applications: Used to model Langmuir oscillations in plasma physics, to investigate conducting polymers, in quantum cohomology, etc. (several monographs about the Toda equation).



In Flaschka's variables

$$a(n,t) = \frac{1}{2}e^{-(q(n+1,t)-q(n,t))/2}, \quad b(n,t) = -\frac{1}{2}\dot{q}(n,t)$$

the Toda equation explicitly reads:

$$\dot{a}(n,t) = a(t) \Big(b(n+1,t) - b(n,t) \Big),$$

 $\dot{b}(n,t) = 2 \Big(a(n,t)^2 - a(n-1,t)^2 \Big).$

Here $\dot{} = \frac{d}{dt}$.

More specific, we consider the Cauchy problem for the Toda lattice equation with initial data which is asymptotically constant

$$a(n,0)
ightarrow rac{1}{2}, \quad b(n,0)
ightarrow 0, \quad ext{as } |n|
ightarrow -\infty.$$

Hence the corresponding operator L is a *small* perturbation of the background operator

$$(L_0y)(n) := \frac{1}{2}y(n-1) + \frac{1}{2}y(n+1).$$

One can show that this asymptotic behavior is preserved by the time evolution.

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• The Toda lattice admits the Lax representation: $\frac{d}{dt}L = [L, P]$,

$$(L(t)y)(n) = a(n-1,t)y(n-1) + b(n,t)y(n) + a(n,t)y(n+1),$$

$$(P(t)y)(n) = -a(n-1,t)y(n-1) + a(n,t)y(n+1).$$

- Spectrum is preserved: L(t) = U(t)L(0)U(-t).
 Here U is the solution of U(t) = P(t)U(t), U(0) = I and is unitary since P is skew-adjoint.
- Infinitely many preserved quantities $tr(L(t)^n L_0^n)$, $n \in \mathbb{N}$.

The initial value problem for the Toda lattice can be solved via the inverse scattering transform:



The long-time asymptotics can then be found via a nonlinear steepest descent analysis (Manakov, Its, Deift & Zhao).

Here we consider the Cauchy problem for the Toda lattice with steplike initial data

$$egin{aligned} &a(n,0)
ightarrow a, \quad b(n,0)
ightarrow b, \quad ext{as } n
ightarrow -\infty, \ &a(n,0)
ightarrow rac{1}{2}, \quad b(n,0)
ightarrow 0, \quad ext{as } n
ightarrow +\infty. \end{aligned}$$

Note that now there are two different background operators. The Toda shock problem is the case satisfying

$$2a + b < -1.$$

Note that the spectra of the two background operators, [b - 2a, b + 2a] and [-1, 1] are nonoverlapping in this case. Hence this condition should be thought of a a condition on the mutual location of the background spectra.

Classical shock problem: $a(n,0) = \frac{1}{2}$, $b(n,0) = \operatorname{sign}(n)b$, b > 1. (Note that b < -1 would be the rarefaction problem.)

Numerically the situation looks as follows:



Problem: Explain/prove this picture.



Numerical investigations

- B. L. Holian and G. K. Straub (1978).
- B. L. Holian, H. Flaschka, and D. W. McLaughlin (1981).

Theoretical

- S. Venakides, P. Deift, and R. Oba (1991)
- A.M. Bloch, Y. Kodama (1991, 1992)
- S. Kamvissis (1993)
- A. Boutet de Monvel, I. Egorova, and E. Khruslov (1997)
- I. Egorova, J. Michor, and G.T. (2018)
- I. Egorova and J. Michor (2021)

Also mentioned in the list of open problems by P. Deift in SIGMA (2017).

Elements of scattering theory



The operator L(t) has a continuous spectrum \mathfrak{S} , $\mathfrak{S} = [b - 2a, b + 2a] \cup [-1, 1]$ and a finite discrete spectrum. The Jacobi equation

$$a(n-1,t)y(n-1) + b(n,t)y(n) + a(n,t)y(n+1) = \lambda y(n)$$

has two Jost solutions

$$\phi(z,n,t)\sim z^n, n\to +\infty, \psi(z,n,t)\sim \zeta^{-n}, n\to -\infty.$$

Two associated Joukowsky transforms of the spectral parameter:



Scattering data

 $W(\tilde{q}) = 0$. Here

$$z([b-2a, b+2a]) = [q_1, q].$$

• Right scattering data (for the initial conditions t = 0):

$$\{R(z), z \in \mathbb{T}; \chi(z), z \in [q_1, q]; z_j, \gamma_j > 0\},\$$

where

$$\chi(z) = 2a \frac{(z - z^{-1})(\zeta(z) - \zeta^{-1}(z))}{|W(z)|^2} = -\overline{T(z)} T_{left}(z),$$

T(z) = T(z, 0) the right transmission coefficient, $\lambda_j = \frac{z_j + z_j^{-1}}{2}$ an eigenvalue and γ_j the corresponding norming constant.

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In Q introduce the vector-function m(z) = m(z, n, t)

$$m(z) = (m_1(z), m_2(z)) = (T(z, t)\psi(n, z, t)z^n, \phi(z, n, t)z^{-n}).$$

The solution $\{a(n, t), b(n, t)\}$ can be obtained from m via:

$$\frac{m_1(0, n, t)}{m_1(0, n+1, t)} = 2a(n, t),$$
$$\lim_{z \to 0} \frac{1}{2z} (m_1(z, n, t)m_2(z, n, t) - 1) = b(n, t).$$

Set $\mathcal{Q}^* = \{z: z^{-1} \in \mathcal{Q}\}$ and extend m(z) to \mathcal{Q}^* by

$$m(z) = m(z^{-1})\sigma_1, \qquad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$



Below is a visualization of the jump contour Σ consisting of the unit circle $\mathbb T$ and two intervals:



Initial RHP



The vector m(z) is the **unique** solution of the following RHP: Find a vector-valued function m which is meromorphic in $Q \cup Q^*$ and continuous up to Σ except at possibly the points $q^{\pm 1}, q_1^{\pm 1}$. It has simple poles at $z_j^{\pm 1}$, $j = 1, \ldots, N$, and satisfies:

• the jump condition: $m_+(z) = m_-(z)v(z)$, where

$$u(z) = \left\{ egin{array}{ll} & \left(egin{array}{ccc} 0 & -\overline{R(z)}\mathrm{e}^{-2t\Phi(z)} \ R(z)\mathrm{e}^{2t\Phi(z)} & 1 \end{array}
ight), & z \in \mathbb{T}, \ & \left(egin{array}{ccc} 1 & 0 \ \chi(z)\mathrm{e}^{2t\Phi(z)} & 1 \end{array}
ight), & z \in [q,q_1], \ & \sigma_1(v(z^{-1}))^{-1}\sigma_1, & z \in [q_1^{-1},q^{-1}]; \end{array}
ight.$$

where

$$\Phi(z):=\Phi(z,\xi)=\frac{1}{2}\big(z-z^{-1}\big)+\xi\log z,\quad \xi:=\frac{n}{t},$$

is the right phase function.

Initial RHP



• the residue conditions:

$$\operatorname{Res}_{z=z_j} m(z) = \lim_{z \to z_j} m(z) \begin{pmatrix} 0 & 0 \\ -z_j \gamma_j e^{2t\Phi(z_j)} & 0 \end{pmatrix},$$
$$\operatorname{Res}_{z=z_j^{-1}} m(z) = \lim_{z \to z_j^{-1}} m(z) \begin{pmatrix} 0 & z_j^{-1} \gamma_j e^{2t\Phi(z_j)} \\ 0 & 0 \end{pmatrix};$$

- the symmetry condition: $m(z^{-1}) = m(z)\sigma_1$.
- the normalization condition: $m_1(0) \cdot m_2(0) = 1$ and $m_1(0) > 0$.
- the resonant/non-resonant condition:
 - If χ(z) = C(z − q̃)^{1/2}(1 + o(1)) at q̃ then m(z) has finite limits m(q̃) as z → q̃, q̃ ∈ {q, q₁}.
 If χ(z) = C/C (1 + o(1)) then

If
$$\chi(z) = \frac{c}{(z-\tilde{q})^{1/2}}(1+o(1))$$
 then

$$egin{aligned} m(z) &= \left(rac{C_1}{(z- ilde q)^{1/2}},\ C_2
ight)(1+o(1)), & C_1C_2
eq 0, ext{ or } \ m(z) &= (C_1,C_2(z- ilde q))(1+o(1)), & z o ilde q, & C_1C_2
eq 0. \end{aligned}$$

At \tilde{q}^{-1} an analog of the above condition holds by symmetry.



Symmetry and normalization conditions:

- We use conjugation/deformation techniques preserving the vector form of the RH problem. To ensure uniqueness we impose the following requirements: I. All contours should be symmetric with respect to the map $z \mapsto z^{-1}$.
- II. For transformations of the form $\tilde{m}(z) = m(z)[d(z)]^{-\sigma_3}$, where $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, and d(z) is a sectionally analytical function, we require: (1) the jump contour $\hat{\Sigma}$ to be symmetric; (2) $d(z^{-1}) = d^{-1}(z)$ for $z \in \mathbb{C} \setminus \hat{\Sigma}$; (3) $d(\infty) > 0$.

Advantage of the vector RHP

- Easy to prove the uniqueness for both, the initial and the model RHPs;
- The matrix statement of the model RHP for the shock wave case does not have invertible solutions in the class of matrices with L^2 -singularities for certain sufficiently large n, t.

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- We work with a vector RHP in comparison to a more common matrix RHP.
- The symmetry condition is important for uniqueness!
- The matrix problem fails to have a nonsingular solution at certain critical parameters (n, t).
- We investigate the problem on an appropriate Riemann surface.



Basic tools:

- Contour deformation (to move the pieces of the jump into regions of the complex domain, where they decay)
- Factorization of the jump matrix (Schur complements) to separate decaying/growing pieces (non-commutativity of matrix multiplication causes problems)
- Conjugation to *replace* the phase function in case the matrices cannot be properly factorized
- Scalar problems can be solved (Sokhotski–Plemelj formulas)
- Problems with constant jumps can be explicitly solved on the Riemann surface

The signature table for the original phase function does not allow for a proper deformation of the RHP.





The key transformation:

$$m(z) \mapsto m(z) \mathrm{e}^{t(g(z)-\Phi(z))\sigma_3}.$$



Consider the Riemann surface associated with the function

$$\mathcal{R}(\lambda) = \sqrt{(\lambda^2 - 1)((\lambda - b)^2 - 4a^2)}.$$

Let Ω_0 be the Abel differential of the second kind with second order poles at ∞_{\pm} and ω be the Abel differential of the third kind with logarithmic poles at ∞_{\pm} , both normalized as $\int_{\mathfrak{a}} \Omega_0 = \int_{\mathfrak{a}} \omega = 0$. The function

$$ilde{g}(\lambda,\xi) = \int_1^\lambda (\Omega_0 + \xi \omega) = \int_1^\lambda rac{(\lambda - \mu_1(\xi))(\lambda - \mu_2(\xi))}{\mathcal{R}(\lambda)} d\lambda,$$

approximates $\Phi(z,\xi)$ as $\lambda o \infty$ up to a constant.

In modulation region with each ξ we associate the Riemann surface for $\mathcal{R}(\lambda,\xi) = \sqrt{(\lambda^2 - 1)(\lambda - b + 2a)(\lambda - \alpha(\xi))}$ and

$$ilde{g}(\lambda,\xi) = \int_1^\lambda (\Omega_0(\xi) + \xi \omega(\xi)) = \int_1^\lambda rac{(\lambda-\mu(\xi))(\lambda-lpha(\xi))d\lambda}{\mathcal{R}(\lambda,\xi)}.$$

The second zero $\alpha(\xi) = \frac{y+y^{-1}}{2} \in (b-2a, b+2a)$ is chosen such that it lies at the branch point!



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- Conjugate to replace Φ by g
- Contour deformation and further conjugations to remove solvable parts (keep singularities under control!)
- Solve the resulting model problem (using theta functions on the elliptic surface)
- Solve the paramtrix problem (to control the difference between the original and the model problem)



Dear Peter, thanks for being such a great colleague and many more happy years!